

# ON COMPUTING EVIDENTIAL CENTROID THROUGH CONJUNCTIVE COMBINATION: AN IMPOSSIBILITY THEOREM

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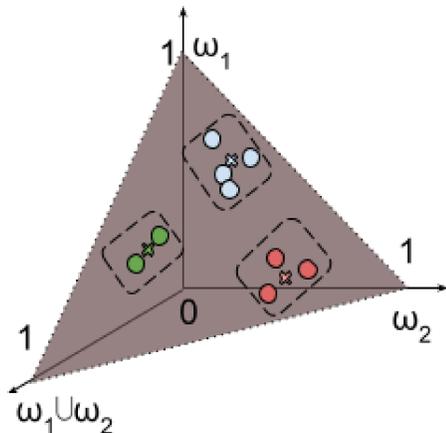
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## Problematic

In the theory of belief function:

- **Combination operation:** fuse information by combining multiple evidence corpus, resulting in a summary of the different pieces of evidence.
- **Distances:** measure dissimilarities between pieces of evidences, which may in turn be used to evaluate source reliability to perform a fusion or combination.



Combination of evidence corpus are used in decision making, while classification/clustering the evidence corpus can be used in grouping the uncertain/imprecise objects.

How the two applications interplay? A common utility between the two is the calculation of centroid. One question:

*Can we use combination rules to compute the centroid of a group of evidence corpus?*

## Properties for combination/centroid calculation

### Centroid of evidence corpus:

Computing the centroid is then the problem of finding the mass  $\bar{m}$ , defined from an arbitrary set  $\{m_1, \dots, m_\ell\}$  of mass functions as:

$$\bar{m} = \arg \min_{m \in \mathcal{E}(\Omega)} \sum_{i=1}^{\ell} d(m_i, m).$$

Usually, to guarantee the convergence of inertia in the iteration of centroid-based clustering, the combination rule must be consistent with a **metric**.

- **Property 1 Metric consistency:** The combination rule  $\odot$  and the dissimilarity measure  $d$  must be consistent. Formally, this means that the combined mass function  $\bar{m}$  calculated by:

$$\bar{m} = \odot_{i=1}^{\ell} m_i,$$

should be the centroid, i.e.,

$$\sum_{i=1}^{\ell} d(m_i, m') > \sum_{i=1}^{\ell} d(m_i, \bar{m}), \quad \forall m' \in \mathcal{E}(\Omega), m' \neq \bar{m}.$$

### Least commitment principle (LCP) in TBF:

When several belief functions are compatible with a set of constraints, the least informative according to some informational ordering (if it exists) should be selected.

LCP is applied in many seminal combination rules, it required the property of **ignorance neutrality**: defined as:

- **Property 2 Ignorance neutrality:** *Vacuous mass functions representing ignorance are neutral elements of the combination rule  $\odot$ , i.e.,*

$$m \odot \Omega^1 = m, \quad \forall m \in \mathcal{E}(\Omega),$$

where  $\Omega^1$  denotes a vacuous mass function.

Another property for cautiousness in an information fusion process.

- **Property 3 Idempotence:** *The combination rule  $\odot$  is idempotent if and only if:*

$$m \odot m = m, \quad \forall m \in \mathcal{E}(\Omega).$$

Indeed, Idempotence is also a **necessary condition** of "metric consistency".

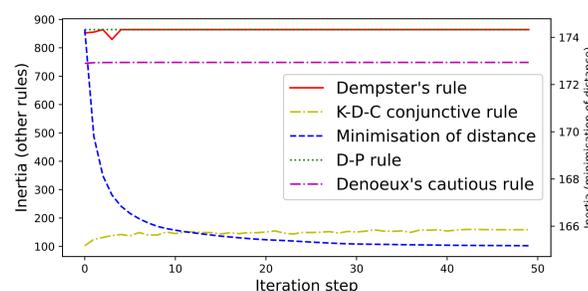
## The impossibility theorem

Given a dissimilarity measure  $d : \mathcal{E}(\Omega) \times \mathcal{E}(\Omega) \rightarrow \mathbb{R}_{\geq 0}$  on the set of evidence corpus, there is no combination rule  $\odot$  that satisfies the properties of **metric consistency** and **ignorance neutrality** simultaneously.

## Case study of combination rules

Properties owned by combination rules:

Combination rules	I.N.	idem.	M.C.
Dempster's rule	T	F	F
Dubois-Prade rule	T	F	F
Denœux's cautious rule	F	T	F
K-D-C conjunctive rule	T	T	F
Minimisation of distance	F	T	T



Inertia of clustering with different combination rules

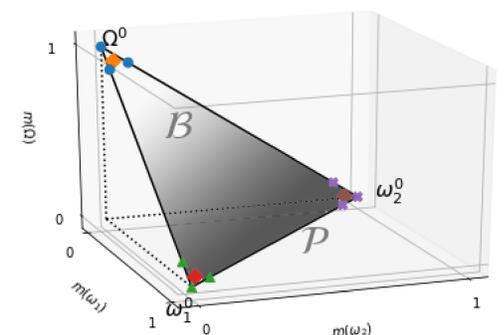
## Different views on clustering evidence corpus

Illustrative data in FoD  $\Omega = \{\omega_1, \omega_2\}$

	Group 1			Group 2			Group 3		
	$m_1$	$m_2$	$m_3$	$m_4$	$m_5$	$m_6$	$m_7$	$m_8$	$m_9$
$m(\omega_1)$	0	0.1	0	0	0.1	0	0.9	0.9	1
$m(\omega_2)$	0.1	0	0	0.9	0.9	1	0	0.1	0
$m(\Omega)$	0.9	0.9	1	0.1	0	0	0.1	0	0

### A metric view

Each evidential corpus is precisely projected into a manifold consistent with a metric. (e.g. Euclidean)



### A conflict-based view

Conflict measure  $\kappa(m_1, m_2)$  on combination rule:

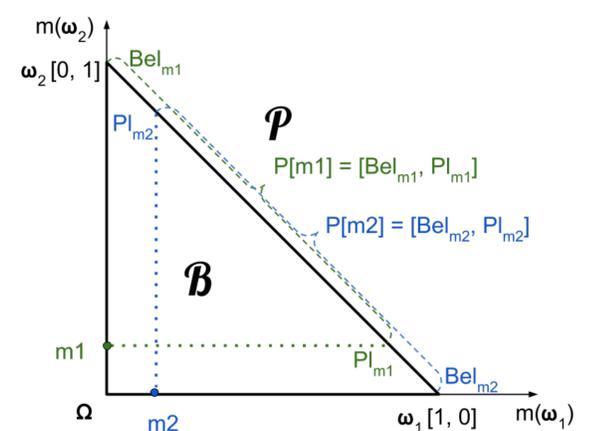
$$\kappa(m_1, m_2) = (m_1 \odot m_2)(\emptyset).$$

$\kappa$	$m_4$	$m_5$	$m_6$	$m_7$	$m_8$	$m_9$
$m_1$	0	0.01	0	0.09	0.09	0.1
$m_2$	0.09	0.09	0.1	0	0.01	0
$m_3$	0	0	0	0	0	0

Remark:  $m_1$  is close to  $m_4 \sim m_6$ ;  $m_2$  is close to  $m_7 \sim m_9$ ;  $m_3$  is close to  $m_4 \sim m_9$ .

### An imprecise probabilistic view

Each mass function is projected as interval probabilistic values, with bounds obtained from belief transform  $Bel$  and plausibility transform  $Pl$ .



Remark: This geometric representation allows to express the uncertainty (by probability) and the imprecision (by interval) simultaneously.

## Conclusion and significance

- Combination rules with LCP are not compatible with any metric;
- Distance-based classification/clustering over evidential corpus is dubious;
- The interpretation of the mass functions must be clarified when selecting a distance.
- Imprecise probabilistic view is appropriate with the original interpretation.

## Questions as perspectives:

- Since no metric is consistent with LCP, how do we theoretically evaluate their effectiveness/correctness?
- How can we relax the properties of metric to make the impossibility possible?
- How to properly classify/cluster objects with uncertainty/imprecision?